

IQanalytics Vandal, Motion and Intrusion Detection

User Guide



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1 Overview

IQanalytics software provides an advanced solution that performs intelligent video analysis and fully automates video monitoring. It automatically tracks and identifies objects, analyzes motion and extracts video intelligence from the camera. These analytics can output real-time events and object data for video data mining or storage in a database. IQanalytics is focused on automating video analysis and security alerts, thus eliminating the need for manual work and huge monitoring costs. It also increases productivity and efficiency of video surveillance systems and the people who monitor them.

The analytics offered are:

- Motion Detection
- Intrusion Detection
- Camera Tamper Detection

Motion Detection

This analytic application analyzes video in real-time and detects valid motion in a scene.

Intrusion Detection

Intrusion detection provides automated perimeter monitoring and secure area protection. It continuously monitors user-selected zones or areas for people or vehicle intrusion. This analytic issues real-time alarms upon detecting true people or vehicle intrusions into a secure area.

Camera Tamper Detector

Camera Tamper Detector monitors the video and automatically detects camera failure or sabotage. It detects any attempts to tamper with the camera--partially or completely blocking its lens or field of view--or drastically changing the camera angle.

2 Installation

If the IQanalytics Application package is not pre-installed on your camera, manual installation will be required. Before installation, please ensure the IQanalytics.iqa application file is available.

- 1. Connect IQeye camera onto the local network
- 2. To help detect camera on local network, use IQeye Auto run CD that is provided with the camera
- 3. Click "Scan for IQeye cameras on my network" to find IP address of the camera.
- 4. Type camera IP address into your browser.
- 5. Go to "setup" tab in camera web UI (if prompted for authentication information, the default username is "root", default password is "system")
- 6. Go to "security" tab in camera web UI
- 7. Click on the application package file in "Application File", select IQanalytics.iqa and press "upload". Please don't switch off or reset camera until uploading and rebooting is complete.
- 8. After uploading, the message "IQanalytics: Installed " in the "Camera Application" section on "security" page should be displayed.
- 9. After installation, if application is not licensed, please contact IQeye for license keys.



3 IQanalytics Configuration

The configuration of IQanalytics parameters can be adjusted using the web user interface. The IQanalytics configuration has the following sections (detailed descriptions are provided in subsequent sections):

- 1. General: Provides general settings for motion detection and video analytics
- 2. Intrusion Provides Intrusion specific settings
- 3. Tamper: Provides Camera Tamper specific settings
- 4. Advanced: Provides Advanced and learning settings for video analytics

Select the IQanalytics app from the 'applications' tab to access the configuration pages.

alicatione: (1909)//ICS V Action:	About
	status: running
	general intrusion tamper advanced
	General Settings
and the second s	motion events enabled
	sensitivity (1100) 80
	Object Size
	Minimum Width, % 15
	Minimum Height, % 25
	Maximum Width, % 30
	Maximum Height, % 80
	apply relearn

General Settings

The following parameters are available for general setting (tuning).

- A. Motion Events: Enable to detect all object enter and object exit events.
- B. Sensitivity: A higher sensitivity value will detect more motion/movements.
- C. Object Sizes: The Object classification table specifies the allowable maximum width-height and minimum width-height parameters applicable for different types of objects. Setting these values, can help fine tune the engine performance. By clicking the check box for different object types, you can enable/disable object detection based on size thresholds.

Object: By clicking the check box , you can enable/disable the object detection

• Object Minimum width: It specifies the minimum allowable width of the object to be detected. It is in terms of percentage

- Object Minimum height: specifies the minimum allowable height of the object to be detected (in terms of percentage)
- Object Maximum width: specifies the maximum allowable width of the object to be detected (in terms of percentage)
- Object Maximum height: specifies the maximum allowable height of the object to be detected (in terms of percentage)

Settings for people, vehicle and other type of objects are similarly setup.

Please note that if more than one type of object is enabled, the entire object (with sizes within the minimum and maximum set values of height-width) will get detected.

Also, if object type 'none' is enabled, all objects regardless of its height-width will be detected.

Intrusion Settings

This page contains Intrusion Detector settings.



A. Enable: will enable the Intrusion detection.

B. Brush: This allows the selection of a brush size for area selection painting.

To select an area for Intrusion Detector, click and drag on the image to paint the scene. The area highlighted in red will be the intrusion area. Click and drag on the red area to de-select that section of the grid.

Camera Tamper Settings

This notifies you when a camera has been tampered with. It looks for blocking, defocusing, power/video loss, light changes and drastic changes in camera angle.





A. Enable: This will enable Camera Tamper Detection.

Ignore Area Settings

Enabling the 'ignore area' allows the engine to ignore processing in areas that don't require it. This may include the ceiling, moving light sources, environmental conditions, or areas where no activity is expected. This allows processing to be reduced and lowers false alarms.



A. Enable: will enable the 'ignore area'.

B. Brush: allows area selection painting to use a larger 3x3 area.

To select an area to ignore, click and drag on the image to paint the scene. The area highlighted in red will be the ignored. Click and drag on the red area to de-select that section of the grid.

Advanced Settings

C. Processing Quality: Select the Processing Quality type from the drop down box depending upon scene. The higher quality allows for detecting smaller objects, however overall accuracy may be reduced as frame rate will be decreased due to additional processing power requirements.

The choices are:

- i. Low (Default Recommended)
- ii. Medium
- iii. High
- iv. Original

Learning Settings

The learning settings effect how IQanalytics learns the background over time. Finetuning these parameters will help in reducing false detections due to scene or environmental changes.

- D. Object Learning: Enable this feature to "learn" stationary objects into the background.
- E. Object Learn Time: The time in seconds a stationary object is in the scene before IQanalytics will "learn" the object into the background.

- F. Sudden Change Learning: Enable this feature to automatically relearn the background if the entire scene changes by more than the specified threshold.
- G. Sudden Change Sensitivity: The percentage of the scene that needs to change before the sudden change learning is triggered.
- H. Default Settings: Resets all parameters back to default settings.
- I. Relearn: Manually relearn the background.

4 Advanced Pages

A few hidden pages are also provided for testing and demo purposes. These pages are not exposed due to its CPU usage, but are useful for testing and demo. It is not recommended to use these pages during production or live deployment.

Events Page

This page displays a list of the most recent events. To access this page, input the following into your web browser http://<ipaddress>:88/event.cgi

Events that are supported:

- Object Entered (iVMD)
- Object Exited (iVMD)
- Intrusion (Intrusion Detector)
- Camera Tampered (Camera Tamper Detector)

It is also possible to store event images and videos upon receiving events from IVA. To enable this feature, please contact Vicon for license details for the events module.

Event ID	Event Description	Object ID	
49	Object Exited	376	
48	Object Entered	376	
47	Object Exited	375	
46	Object Entered	375	
45	Object Exited	374	
44	Object Entered	374	
43	Object Exited	373	
42	Object Entered	373	
41	Object Exited	372	
40	Object Entered	372	
39	Object Exited	371	
38	Object Entered	371	
37	Object Exited	370	
36	Object Entered	370	
35	Object Exited	369	
34	Object Entered	369	
33	Object Exited	368	
32	Object Entered	368	
31	Object Exited	367	
30	Object Entered	367	
29	Object Exited	366	

5 Camera Placement & Guidelines

This section provides recommended camera angles and positions.

Camera Positioning

Camera positioning is critical for capturing good data for video analytics. Care should be taken to avoid a) object size being set too large, and b) occlusions.

Typically, cameras should be installed with one of three views:

- 1. Top-Down view (vertical ceiling mount)
- 2. Perspective or Angled view (wall or corner mount looking down) Useful for detecting general intrusion.
- 3. Side View (horizontal wall mount at lower height).

The Top-Down View is generally good for counting, detecting direction of movement, etc. The second option (perspective or angle view) is good for detecting intrusions. The third option (side view) should only be used for face detection. It is not recommended for other analytics since objects can be hidden from view (occlusions).

FOV (Field of View) and Object Size

For people detection, the object or person size should be 10-20% of the whole scene. The object size should not be set to occupy 40-100% of the scene.

Recommended Scene and Lighting Conditions

General recommendations for lighting when using video analytics.

- 1. The scene should be well-lit. Low lighting levels produce video noise that can triggers false object alerts.
- 2. Stable and consistent lighting will provide good results. Fluctuations in lighting or uneven lighting at the scene will cause false alarms in any video analytics system.
- 3. If providing appropriate lighting is an issue, it is recommended that a camera with IR illumination be used.
- 4. Avoid occlusions (one object going in front of another). This will break object tracks and will cause object disappearance and other related problems.
- 5. Avoid pointing the camera directly at light sources as described below. The following situations will make the video unusable for analytics and will temporarily signal saturation.
 - a. Camera pointed directly at the sun.
 - b. Camera pointed directly at light source
 - c. Camera looking at vehicles with headlights (cars, trains in tunnels)
- 6. Avoid or minimize shadows by repositioning the camera or light source(s).
- If possible avoid the presence of trees and other vegetation in the camera's field of view. Swaying or movement of trees and bushes in the wind can cause false alarms. If they cannot be avoided, use 'ignore area' – these zones will be ignored during processing.
- If possible, avoid the presence of water areas rivers, lakes etc. in the camera's field of view. Water areas can cause reflections and ripples that can cause false alarms. If they cannot be avoided, use 'ignore area' – these zones will be ignored during processing.

- 9. Ensure that the size of the objects that are to be tracked in the scene are not too small. Object sizes have to be at least 5-10% of the scene for consistent detection. If the objects are only a few pixels (people or vehicles), it will be difficult to detect them consistently and will cause false alarms on most systems.
- 10. Ensure that the object size is not too large more than 40% of the scene. The camera should not be too close to the objects being tracked.
- 11. We recommend you turn off AGC (Auto Gain), Auto IRIS and White Balance on cameras. These fluctuate some times and cause notable scene changes. It is possible to run the system with these settings ON, with lower sensitivity, if the scene is stable and fluctuations are infrequent.
- 12. Camera lenses need to be kept clean and focused for best results.

Camera Zoom, FOV and Angle are important. The following sections address them fully with examples.

Recommended Camera Positioning for Common Applications

1. Intrusion Detector

Camera must be at an angle looking down. Camera should be installed at sufficient height to avoid occlusions. The object size should not be too large relative to the scene. It is recommended that the size of any object entering the scene not exceed 50% of the scene size.

If the camera is used during the night, lighting reflections should be minimized to avoid false detections. Light should be uniformly distributed in the scene (avoid shadows). In addition, ensure no light sources are directed at the camera.

A camera that is pointed at an angle looking down is optimal for intrusion detection, as seen below.



Intrusion



Angled View

2. Camera Tamper Detector

For tamper detection, the camera can be installed in any position; top-down view, side view or front view. The maximum size of objects entering the scene should not exceed 50-60% of scene size. If the camera is used during the night, lighting reflections should be minimized to avoid false detections. Light should be uniformly distributed in the scene (avoid shadows). In addition, ensure no light sources are directed at the camera.



6 Recommended Settings

Overview

The performance of the video analytics engine relies greatly on scene type and the settings applied to those scenes. This section provides a collection of common scenes and the corresponding recommended settings for each. These recommended settings are meant to be used only as a guide toward obtaining more accurate results. Since every scene is different, the recommended settings do not show specific values. They are simply a guide to what settings need to be adjusted for in different scenarios to improve on certain aspects of the results.

Adjusting Basic Settings

For some scenes, the default settings should be sufficient without changing anything other than minimum and maximum object sizes, and sensitivity. For example:

Different Environment Conditions	Default Settings Image	Recommended Settings	Modified Settings Image
Two objects detected as one	In this scene, two objects are being detected as one. This is usually due to the maximum size of objects not set correctly. In this situation, reduce the maximum size of objects	A typical rule of thumb when setting minimum and maximum sizes is to set the minimum size of an object to half the width and height of the average object, and the maximum size of an object to about 130% the width and height of the average object.	We can see that adjusting the maximum size allows the two persons to be detected as separate objects.

One object detected as two	In this scene, one object is detected as two separate objects. This is usually due to the minimum and/or maximum size set incorrectly. In this situation, increase the minimum and/or maximum size of objects accordingly to accommodate larger objects.	A typical rule of thumb when setting minimum and maximum sizes is to set the minimum size of an object to half the width and height of the average object, and the maximum size of an object to about 130% the width and height of the average object.	We can see that increasing the minimum and maximum size allows the object to be correctly detected as one.
High Video Noise	In some scenes, the video contains a high amount of noise that greatly affects the engine by causing unwanted objects to be detected and/or trigger unwanted events	To minimize the effects of noise, Sensitivity can be reduced so that only more prominent objects will be detected and trigger events.	The result from these settings allows the engine to ignore video noise and still be able to detect objects in the scene.

Adjusting Advanced Settings

Some scenes require extra or advanced settings like continuous learning, shadow suppression etc.

Continuous Learning

This feature allows the engine to learn the scene as it changes gradually. Learning happens in every frame and gradual changes in background are captured. This feature is typically used for scenes such as:

- 1. Outdoor scenes with shadows
- 2. Indoor scenes with changing lighting conditions
- 3. Parking areas

There are other features involved in continuous learning, such as learn object, learning time, learn scene, etc. For example:

Different Environment Conditions	Default Settings Image	Recommended Settings	Modified Settings Result
Indoor scene with changing lighting condition.	In this scene, lighting condition changes frequently due to lights being turned off and on by a sensor.	In order to accommodate sudden changes in the scene due to lighting conditions, Scene Change Based Learning can be turned on. Sensitivity can also be reduced to reduce false alarms due to lighting changes. If Camera Tamper feature is turned on, sudden changes in the scene will cause the "Scene Change" event to trigger.	VotestinicocchargingUgetingcover() Object D. Image: Constraint of the constraint

Scene with moving trees	This outdoor scene includes a lot of unwanted movement from trees and shrubbery. These movements can cause the engine to detect them as objects and trigger unwanted events.	In order to avoid detection of tree movement, Sensitivity can be reduced to avoid the trees from triggering any events. Another solution is to set the area around the trees as "Ignored Area"	These settings will allow the engine to avoid detecting the movement from the trees.
Scene with cars parking for extended period of time	This scene shows a car arriving at a parking lot and parks for a long period of time. By default, the car would get absorbed/learned into the background after a set amount of time. In some situations, these objects need to be tracked even though they are not moving.	To accommodate objects arriving at the scene and staying for long periods of time, the "Object Learning" feature can be turned on.	The result of these settings would allow the engine to track the cars that have parked for a long period of time without them being learned into the background.
Night Time/Low Contrast	This scene is set at night time. Objects are not as prominent at low light situations, and sometimes the engine might not be able to detect them as intended.	In scenes with low contrast and low light, sensitivity needs to be increased. While sensitivity is set to high, it is also advisable to turn on the "Continuous Learning" feature to decrease false detections.	This results in objects being detected properly in low light conditions.

